

**A SYSTEM AND METHOD FOR DRAWING AND PAINTING  
WITH WARPED BITMAP BRUSHES**

**TECHNICAL FIELD**

5 This invention relates generally to displaying art and information in computing environment and, more particularly, relates to rendering graphic output along a curving baseline defining a stroke path.

**RELATED APPLICATIONS**

This application claims priority from the patent application 09/224,237 (attorney  
10 docket number 187832), by John Bronskill, filed on December 30, 1998 in the United States Patent and Trademark Office.

**BACKGROUND OF THE INVENTION**

Since the first incarnation of digital paint systems, there has been a lot of work to make synthesized paint strokes, i.e., virtual painting on a computer, look like those  
15 created using traditional paint and drawing tools, for example, watercolor brushes, chalk strokes, etc. In particular, two known commercial products, "PAINTER" and "EXPRESSION" sold by MetaCreations, provide tools for use in creating "natural media" digital painting and drawing. "PAINTER" is raster based and uses procedural algorithms to generate paint strokes that give the appearance that they have been created  
20 by their real world counterpart. "EXPRESSION" is vector based and uses "skeletal strokes" technology.

Skeletal strokes, described in S. C. Hsu and I. H. H. Lee, "*Drawing and Animation Using Skeletal Strokes*," SIGGRAPH '94 Conference Proceedings, July 1994

and S. C. Hsu, I. H. H. Lee, and N. E. Wiseman, "*Skeletal Strokes*," UIST '93

Proceedings of the ACM SIGGRAPH and SIGCHI Symposium on User Interface

Software Technology, November 1993, utilizes a vector graphics realization of the brush

and stroke metaphor using arbitrary pictures as "ink." Generally, defining a skeletal

5 stroke requires drawing an instance of the flesh, which could be any arbitrary picture,

around a reference line. The reference line provides a reference x-axis for the points

specifying the position of the flesh; a reference thickness provides a scale to specify the

lateral distance of these points from the reference line. A picture so anchored to a single

reference line defines a skeletal stroke. Once a skeletal stroke is defined, it can be

10 applied along any arbitrary path by simply drawing the path and aligning the reference

line of the skeletal stroke with the given path. In this manner, the flesh is distorted

(stretched, compressed, bent and/or sheared) to generally follow the path.

It should be noted that it is possible to distort or warp images without reference to

a specified reference line. As an example, the United States Patent No. 5,920,327 issued

15 to Robert Seidensticker, Jr., describes rendering graphical objects at different resolutions

within the same image to generate a 'fish-eye' view. It does not, however, teach

techniques for rendering graphics relative to arbitrarily curved baselines or other

reference lines.

While these tools generally work for their intended purpose, both "PAINTER"

20 and "EXPRESSION" tend to fall short in terms of the realism of the paint stroke

synthesized. In particular, because of the procedural nature of "PAINTER" and the

vector nature of "EXPRESSION", the paint strokes produced lack the subtle flaws and

detail of real brush strokes or real objects. Accordingly, a need exists for an apparatus

and method for digitally producing brush strokes that appear to be hand drawn and painted. It is also desirable to reduce the computational effort in providing such functionality in order to provide responsive applications that can be executed on a broad range of systems (as opposed to high end computing machines).

- 5           In many embodiments the paint brush may be specified by a bitmap, termed a bitmap brush that can be treated as a two-dimensional object. Two-dimensional graphical objects are customarily transformed using affine transformations, such as scaling, rotating, skewing, and translating. In addition, non-affine transformations, such as texture mapping, bilinear and perspective transforms, are available that can actually
- 10   “warp” the graphical object. For instance, in a bilinear transform, a rectangle is transformed into a “quad,” i.e., a quadrilateral, such that any point along the edge of the rectangle becomes a point on the edge of the quad while retaining its relative position. Points within the rectangle are similarly distorted or warped in their relative positions. It is convenient to regard bilinear transforms as preserving equally spaced points along a
- 15   line but not necessarily preserving diagonal straight lines as straight lines.

- A brush stroke can be imagined to be along a path connecting two endpoints. Such a path may be imagined to have a width and a curvature, including sharp turns. The width may be constant or it may vary in a prescribed manner, e.g., as a function of the local curvature or some other rule. The brush itself may be an image to be warped or a
- 20   set of tiles to be arranged along the path prescribed by a guideline, which includes information about the path and the thickness of the desired brush stroke.

### SUMMARY OF THE INVENTION

The invention describes a method and system for rendering a warped brush stroke using a bitmap brush image, the brush stroke being along a arbitrarily curved guideline. The method and system generate a piecewise linear approximation, consisting of linear segments, to the guideline followed by generating convex polygons with the aid of the  
5 linear segments such that contiguous linear segments have contiguous polygons. A mapping is identified between segments of the bitmap brush and the polygons such that the corners or the boundaries of a segment of the bitmap brush map to the corners or boundaries of a corresponding polygon. The collection of polygons, so rendered, define  
10 the warped brush stroke.

Specifically, a segment of the bitmap brush is mapped into a corresponding polygon using transformations that do not require visiting any pixel in the warped brush stroke more than once. Examples of such transformations include the bilinear transformation, which defines a mapping between a bitmap brush segment having four  
15 corners and a polygon in the warped brush stroke having four corners. Thus, this is a mapping between quads where quads include squares, rectangles and quadrilaterals. Another useful transformation – more general than the bilinear transformation - is texture mapping, which allows mapping between polygons having different number of corners. In addition, tiling, using one or more segments of the bitmap brush, may be used to  
20 preserve sufficient detail in the warped brush stroke while allowing rendering of an extended warped brush stroke.

Additional features and advantages of the invention will be made apparent from the following detailed description of illustrative embodiments which proceeds with reference to the accompanying figures.

### **BRIEF DESCRIPTION OF THE DRAWINGS**

**[Please provide figure originals as prints with sufficient detail to allow good reproductions to be made. Your generous offer is greatly appreciated.]** While the  
5 appended claims set forth the features of the present invention with particularity, the invention, together with its objects and advantages, may be best understood from the following detailed description taken in conjunction with the accompanying drawings of which:

Figure 1 is a block diagram generally illustrating an exemplary computer system  
10 on which the present invention resides;

Figure 2 is an illustration of a "sumi-e" bitmap brush;

Figure 3 is an illustration of a "watercolor" bitmap brush;

Figure 4 is an illustration of a "chain" bitmap brush;

Figure 5 is an illustration of a "rope" bitmap brush;

15 Figure 6 is an illustration of the "sumi-e" bitmap brush of Fig. 2 disposed in a Cartesian coordinate system;

Figure 7 is an illustration of the "sumi-e" bitmap brush of Fig. 2 warped along a guideline specifying a constant thickness continuous brush stroke;

Figure 8 is a graphical representation of a forward approach to mapping a bitmap  
20 brush image to a guideline;

Figure 9 is an illustration of the graphical representation of a point in the guideline in the Cartesian coordinate system;

Figure 10 is an illustration of a backward approach to mapping a bitmap brush image to a guideline;

Figure 11 is an illustration of a bitmap brush before and after being mapped to a guideline using a tiling method;

5        Figure 12 is an illustration of a warped brush stroke showing the compositing of paint strokes;

Figure 13 is a flow chart listing broad outlines of a method for making a warped brush stroke without showing the compositing of paint strokes;

10       Figure 14 illustrates a line in a guideline being piecewise approximated by end-to-end connected linear segments;

Figure 15 illustrates the linear segments of figure 14 being used to create a sequence of quadrilaterals;

Figure 16 illustrates a more extensive set of polygons corresponding to a guideline having a constant thickness;

15       Figure 17 illustrates a set of polygons corresponding to a guideline specified by two lines to specify variable thickness for a brush stroke along the stroke;

Figure 18 illustrates the problem posed by sharp corners for constructing polygons;

20       Figure 19 illustrates the problem posed by overlapping polygons at a sharp turn in the guideline;

Figure 20 is an illustration of a smoothing out of the sharp corner illustrated in figure 18;

Figure 21 illustrates a truncation strategy for handling overlapping polygons at sharp turns in the guideline;

Figure 22 is an illustration of the mapping of polygons corresponding to a guideline and a sequence of corresponding segments in a bitmap brush;

5        Figure 23 illustrates the mapping from one segment of a bitmap brush to a polygon;

Figure 24 is an illustration of warped brush strokes applied to a clip art image;

Figure 25 is an illustration of a "checker board" bitmap brush before and after being mapped to a guideline; and

10        Figure 26 illustrates a possible system and method in accordance with the invention.

### **DETAILED DESCRIPTION OF THE INVENTION**

Turning to the drawings, wherein like reference numerals refer to like elements, 15 the invention is illustrated as being implemented in a suitable computing environment. Although not required, the invention will be described in the general context of computer-executable instructions, such as program modules, being executed in a computing environment. Generally, program modules include routines, programs, objects, components, data structures, etc. that perform particular tasks or implement particular 20 abstract data types. Moreover, those skilled in the art will appreciate that the invention may be practiced with other computer system configurations, including hand-held devices, multi-processor systems, microprocessor based or programmable consumer electronics, network PCs, minicomputers, mainframe computers, and the like. The

invention may also be practiced in distributed computing environments where tasks are performed by remote processing devices that are linked through a communications network. In a distributed computing environment, program modules may be located in both local and remote memory storage devices.

5           With reference to Figure 1, an exemplary system for implementing the invention includes a general purpose computing device in the form of a conventional computing environment 20, including a processing unit 21, a system memory 22, and a system bus 23 that couples various system components including the system memory to the processing unit 21. The system bus 23 may be any of several types of bus structures  
10 including a memory bus or memory controller, a peripheral bus, and a local bus using any of a variety of bus architectures. The system memory includes read only memory (ROM) 24 and random access memory (RAM) 25. A basic input/output system (BIOS) 26, containing the basic routines that help to transfer information between elements within the computing environment 20, such as during start-up, is stored in ROM 24. The  
15 computing environment 20 further includes a hard disk drive 27 for reading from and writing to a hard disk 60, a magnetic disk drive 28 for reading from or writing to a removable magnetic disk 29, and an optical disk drive 30 for reading from or writing to a removable optical disk 31 such as a CD ROM or other optical media.

          The hard disk drive 27, magnetic disk drive 28, and optical disk drive 30 are  
20 connected to the system bus 23 by a hard disk drive interface 32, a magnetic disk drive interface 33, and an optical disk drive interface 34, respectively. The drives and their associated computer-readable media provide nonvolatile storage of computer readable instructions, data structures, program modules and other data for the computing



environment 20. Although the exemplary environment described herein employs a hard disk 60, a removable magnetic disk 29, and a removable optical disk 31, it will be appreciated by those skilled in the art that other types of computer readable media which can store data that is accessible by a computer, such as magnetic cassettes, flash memory cards, digital video disks, Bernoulli cartridges, random access memories, read only memories, and the like may also be used in the exemplary operating environment.

Computing environment 20 includes computer readable media includes volatile and nonvolatile, removable and non-removable media implemented in any technology or method for information storage such as computer instructions, data structures, program modules and the like. Computer storage media includes, but is not limited to, RAM, ROM, EEPROM, flash memory, or other memory technology, CD-ROM, Digital versatile disks ("DVD") etc. that can be used to store and access the information. Communication media typically includes computer readable instructions, data structures, program modules or data in a modulated data signal such as a carrier wave.

A number of program modules may be stored on the hard disk 60, magnetic disk 29, optical disk 31, ROM 24 or RAM 25, including an operating system 35, one or more applications programs 36, other program modules 37, and program data 38. A user may enter commands and information into the personal computer 20 through input devices such as a keyboard 40 and a pointing device 42. Other input devices (not shown) may include a microphone, joystick, game pad, satellite dish, scanner, or the like. These and other input devices are often connected to the processing unit 21 through a serial port interface 46 that is coupled to the system bus, but may be connected by other interfaces, such as a parallel port, game port or a universal serial bus (USB). A monitor 47 or other

type of display device is also connected to the system bus 23 via an interface, such as a video adapter 48. In addition to the monitor, personal computers typically include other peripheral output devices, not shown, such as speakers and printers.

The computing environment 20 may operate in a networked environment using  
5 logical connections to one or more remote computers, such as a remote computer 49. The remote computer 49 may be a personal computer, a server, a router, a network PC, a peer device or other common network node, and typically includes many or all of the elements described above relative to the computing environment 20, although only a memory storage device 50 has been illustrated in Fig. 1. The logical connections depicted in Fig.  
10 1 include a local area network (LAN) 51 and a wide area network (WAN) 52. Such networking environments are commonplace in offices, enterprise-wide computer networks, intranets and the Internet.

When used in a LAN networking environment, the personal computer 20 is connected to the local network 51 through a network interface or adapter 53. When used  
15 in a WAN networking environment, the computing environment 20 typically includes a modem 54 or other means for establishing communications over the WAN 52. The modem 54, which may be internal or external, is connected to the system bus 23 via the serial port interface 46. In a networked environment, program modules depicted relative to the computing environment 20, or portions thereof, may be stored in the remote  
20 memory storage device. It will be appreciated that the network connections shown are exemplary and other means of establishing a communications link between the computers may be used.

In the description that follows, the invention will be described with reference to acts and symbolic representations of operations that are performed by one or more computer, unless indicated otherwise. As such, it will be understood that such acts and operations, which are at times referred to as being computer-executed, include the manipulation by the processing unit of the computer of electrical signals representing data in a structured form. This manipulation transforms the data or maintains it at locations in the memory system of the computer, which reconfigures or otherwise alters the operation of the computer in a manner well understood by those skilled in the art. The data structures where data is maintained are physical locations of the memory that have particular properties defined by the format of the data. However, while the invention is being described in the foregoing context, it is not meant to be limiting as those of skill in the art will appreciate that various of the acts and operation described hereinafter may also be implemented in hardware.

In accordance with the invention, a system and method is provided for allowing a user to paint and draw with a scanned bitmap brush. To create the paint stroke, the bitmap brush is mapped to and warped along the path of a predefined guideline stroke. The bitmap brush may be an "artistic brush" that is a scanned bitmap image of an actual artistic stroke created in a variety of styles including watercolor, oil, chalk, crayon, ink, etc. An exemplary "sumi-e" bitmap brush is illustrated in Fig. 2 while an exemplary "watercolor" bitmap brush is illustrated in Fig. 3. Additionally, the bitmap brush may be a "photo brush" that is a scanned bitmap image of an object such as a rope, wire, chain etc. An exemplary "chain" bitmap brush is illustrated in Fig. 4 while an exemplary "rope" bitmap brush is illustrated in Fig. 5. While it is preferred that the bitmap brushes

be created using well known scanning processes, it will be appreciated that other known methods are available for creating the bitmap brush images. Accordingly, the invention is not intended to be limited to any particular manner by which the bitmap brushes are created.

5           The predefined guideline over which the bitmap brushes are mapped to create the artistic stroke can be drawn using any currently available, digital painting tool, be extracted from provided clip art images, etc. Additionally, the predefined guideline can be of any thickness and include any number of curves. While the height of the bitmap brush is a constant in many of the embodiments it is possible to vary the thickness of the

10   brush stroke. For instance, use of an input, e.g., pressure, to vary the thickness of the brush stroke at a particular point along the brush stroke allows generation of a pair of lines defining the thickness of the brush. From another perspective, this may be treated as specifying a desired height/thickness for the warped stroke at selected points along the guideline. In embodiments where the brush stroke is specified algebraically such a

15   specification could reflect a desired pressure profile. A simple example may have two lines, not necessarily parallel to each other, in the guideline to specify the upper and lower edges of the warped stroke made using the bitmap brush. Accordingly, the invention is not intended to be limited to any particular manner by which the predefined guideline is created or the height/thickness of the brush stroke specified.

20           The mapping and warping of the generally rectangular bitmap brush along the predefined guideline to create the paint stroke is generally accomplished by transforming the Cartesian ( $x$ ,  $y$ ) coordinate system of the bitmap brush such that the  $x$ -axis of the bitmap brush is aligned with the path  $Q(t)$  of the guideline and the  $y$ -axis of the bitmap

brush is aligned with the instantaneous normal  $n$  to the path  $Q(t)$  of the guideline. The pre-transformation coordinate system for a “sumi-e” bitmap brush having a width in pixels  $W$  and a height in pixels  $H$  is illustrated in Fig. 6. The transformed “sumi-e”

bitmap brush that has been warped along the guideline having a width in pixels  $T$  to

5 create a paint stroke is illustrated in Fig. 7. As seen in Fig. 7, the instantaneous normal  $n$  is perpendicular to the path  $Q(t)$  of the guideline at each point  $P$ , that comprises the path  $Q(t)$ . An exemplary method by which such a coordinate transformation may be

performed is described in S. C. Hsu, I. H. H. Lee, and N. E. Wiseman, “*Skeletal Strokes*,”

USIT '93 Proceedings of the ACM SIGGRAPH and SIGCHI Symposium on User

10 Interface Software and Technology, November 1993.

More specifically, to map and warp the bitmap brush to the two dimensional continuous curves of the guideline, the path  $Q(t) = \{x(t), y(t)\}$  of the guideline is first expressed in parametric form with parameter  $t$  ( $0 \leq t \leq 1$ ) such that the start of the path  $Q(t)$  is at  $t = 0$  and the end of the path  $Q(t)$  is at  $t = 1$ . This is illustrated in Fig. 8. A

15 method for expressing the path  $Q(t)$  of a guideline in parametric form is described in greater detail in J. Foley, A. Van Dam, S. Feiner, and J. Hughes, “*Computer Graphics Principles and Practice*,” 2<sup>nd</sup> Edition, Addison-Wesley, 1990. Preferably, each guideline has a continuous first derivative  $Q'(t) = \{x'(t), y'(t)\}$  and second derivative  $Q''(t) =$

$\{x''(t), y''(t)\}$ . Details pertaining to the calculation of the derivatives and the like are

20 described in G. Farin, “*Curves and Surfaces for CAGD – A Practical Guide*,” 4<sup>th</sup> Edition, Academic Press, 1997. A familiar example of such a guideline is a two-dimensional cubic Bezier curve. It should be noted that a guideline having a continuous first derivative is not a requirement, but instead, a preference in some embodiments.

Having defined the path  $Q(t)$  of the guideline in parametric form, the points  $P_{t,n}$  that comprise the predefined guideline are defined. Letting  $W$  and  $H$  be the width and height of the bitmap brush in pixels, respectively,  $L$  be the arc length of the path  $Q(t)$  of the guideline in pixels,  $T$  be the thickness of the guideline in pixels, and  $R$  be a rectangular region that fully encloses the path  $Q(t)$  if it is drawn with a stroke thickness  $T$ , a point  $P_{t,n}$  on the guideline a distance  $d$  from  $Q(t)$  can be defined by the expression:

$$P(x, y) = Q(t) + d\hat{n}(t) \quad (1)$$

where  $0 \leq t \leq 1$ ,  $-T/2 \leq d \leq T/2$ , and  $\hat{n}(t)$  is the unit normal vector to  $Q(t)$ . The graphical representation of this definition of a point of the guideline is illustrated in Fig. 9.

Expanding the equation, it can be expressed as:

$$P(x, y) = (x(t), y(t)) + d(y'(t), -x'(t)) / \sqrt{x'^2(t) + y'^2(t)} \quad (2)$$

In this manner, each point  $P_{t,n}$  that comprises the guideline can be mapped to a Cartesian coordinate location  $P(x, y)$  within the rectangle  $R$ .

Using the relationship between the points  $P_{t,n}$  that define the guideline and the locations  $P(x, y)$  defining the rectangle, there are two alternative approaches that can be taken to complete the mapping of the pixels that comprise the bitmap brush to the points  $P_{t,n}$  that comprise the guideline. Without any loss in generality these are described in the context of warped brush strokes of constant width and with only one line in the guideline. Generally, in the forward mapping approach, equation (2) is used and  $t$  and  $d$  are varied over all possible values. In the backward mapping approach, the point  $P(x, y)$  is started with and  $t$  and  $d$  are solved for known  $x(t)$ ,  $y(t)$ ,  $x'(t)$ , and  $y'(t)$ .

The bitmap brush pixel look-up is performed using the height ( $H$  pixels) and the width ( $W$  pixels) of the bitmap brush. It will be appreciated that the  $(X, Y)$  address of the

pixel within the bitmap brush derived from the foregoing procedure may not be a integral value. As a result, interpolation techniques such as nearest neighbor, bilinear, bicubic convolution or other methods should be employed. Examples of such interpolation techniques may be found in A. Rosenfeld and A. Kak, "*Digital Picture Processing*," Vol.

- 5 2, 2<sup>nd</sup> Edition, Academic Press, 1982. Furthermore, to minimize distortion, it is preferred that the brush image should be scaled such that  $H$  is equal to  $T$  and  $W$  is equal to  $L$ .

Known methods for performing these scaling operations are described in D. Schumacher, "*General Filtered Image Rescaling*," Graphics Gems III (D. Kirk ed.), Academic Press, Inc. 1992.

- 10 An accumulation table into which the looked-up pixel values are stored is configured to have an entry in the form of an accumulation buffer for each point  $P(x,y)$  in the rectangle  $R$ . Upon completion of the accumulation process for all values  $t$  and  $n$ , the values for the pixels stored in the accumulation table are mapped to the corresponding  $P(x,y)$  location within the rectangle  $R$  to create the paint stroke. It will be understood that
- 15 the pixels corresponding to the guideline are removed from the rectangle  $R$  during this mapping process.

In the backward mapping approach, illustrated in Figs. 10, for each pixel  $P(x,y)$  within the rectangle  $R$  points  $Pt_x$  are computed from the points  $P_i$  which comprise the path  $Q(t)$  that are nearest to  $P(x,y)$  in both Cartesian coordinates and parametric coordinates.

- 20 An algorithm for performing this computation using Bezier curves may be found in P. J. Schneider, "*Solving the Nearest-Point-On-Curve-Problem*," in Graphics Gems, Academic Press, 1990. Generally, for Bezier curves of degree three, there may be between zero and five points  $Pt_x$  ( $0 \leq x \leq 5$ ) on the path  $Q(t)$  that are nearest to  $P(x,y)$ .

Unlike the backward mapping approach where each pixel  $P(x,y)$  is ensured of being assigned a pixel value, it is possible that the forward mapping approach may miss some pixels  $P(x,y)$  and hit some pixels  $P(x,y)$  more often than necessary. To minimize this result, the sample rates  $\Delta t$  and  $\Delta n$  are preferably set small enough such that

- 5 substantially every pixel in the guideline stroke is hit but not so small that excessive work is being done. Accordingly, a nominal value for  $\Delta t$  that is seen to be effective for relatively straight portions of the guideline path  $Q(t)$  is  $\Delta t = 1.0/(1.8 * L)$ .

- As will be appreciated, however, this sample interval should be decreased as the radius of curvature of the guideline decreases. This results from the fact that the more the
- 10 radius of curvature of the guideline decreases, the more the angles of the normals  $n$  for each point  $P_i$  that comprise the curve will vary with respect to one another thus increasing the likelihood that pixels  $P(x,y)$  are missed or over sampled. A method for calculating the radius of curvature which can then be compared against a series of thresholds for adjusting the sampling rate  $\Delta t$  may be found in G. Farin, "*Curves and Surfaces for CAGD*
- 15 – *A Practical Guide*," 4<sup>th</sup> Edition, Academic Press, 1997. A preferred sample rate along the normal  $n$  is preferably set as  $\Delta n = 1.0/(1.3 * T)$ . Additionally, when the desired thickness  $T/2$  exceeds the radius of curvature along any point  $P_i$  on the path  $Q(t)$ , unwanted visual artifacts may result. When this condition occurs in the forward mapping process, point  $B$  or  $C$  (depending on which side of the path  $Q(t)$  is concave) is preferably
- 20 limited to the center of curvature of the path  $Q(t)$  for that point  $P_i$ .

In an alternative embodiment, instead of stretching or shrinking the entire length of the bitmap brush to substantially match the arc length of the guideline, it is possible to tile the bitmap brush in the x-direction. By way of example, given a guideline having an



arc length of 400 pixels and a bitmap brush having a length of 200 pixels, it is possible to map the bitmap brush twice to the guideline (the bitmap brush being mapped once along the path  $Q(t)$  from  $0 \leq t \leq 0.5$  and once again from  $0.5 < t \leq 1.0$ ). To minimize distortion, it is again preferred that the brush image be scaled such that  $H$  is equal to  $T$  and  $W$  is equal to  $L/(\text{the number of tiles desired})$ . This method of mapping the bitmap brush is especially desirable for bitmap photo brushes, such as the "chain" bitmap brush illustrated in Fig. 4, whereby the number of links of the chain ultimately drawn will increase as a function of the length of the guideline. As will be appreciated, using the formerly described method of mapping the bitmap brush, wherein the bitmap brush is singularly mapped over the entire arc length of the guideline, would result in the rendering of a chain having the same number of chain links as are in the scanned "chain" bitmap brush image but would cause those chain links to lengthen as a function of the arc length of the guideline.

Still further, instead of mapping the entire length of the bitmap brush to the arc length of the guideline, it is possible to have a bitmap brush that has portions that tile in the x-direction. By way of example only, it is possible to have a bitmap brush, such as the "crayon" bitmap brush illustrated in Fig. 11, in which the middle section is tiled in the manner previously described while the head and tail sections are mapped to corresponding end portions of the path  $Q(t)$  such that the head and tail sections of the bitmap brush are stretched in the x-direction as little as possible when the paint stroke is completed while generally maintaining the overall proportions of the end sections. As will be apparent, this is particularly desirable for use in connection with bitmap brushes

that have unique head and tail images, for example, the crayon illustrated in Fig. 11, a rope having tassels at either end, etc.

It is preferred that the pixels that comprise bitmap brush have color channels, such as RGB or CMYK, and, optionally, an alpha (transparency) channel. In this manner, both the forward and mapping approaches result in a warped image that can be composited onto any background image. This also allows multiple strokes to be drawn in a back to front manner by compositing one over another. An exemplary result of utilizing this method on clip art is illustrated in Fig. 12 wherein, it is preferred that, should any paths overlap, the algorithm selected is applied to each of the paths in a back to front manner so that the paths that are higher in the stacking order are composited over paths that are lower in the stacking order. An exemplary set of procedures for compositing digital images is provided in T Porter and T. Duff, "*Compositing Digital Images*," Proceedings of SIGGRAPH, pages 253-259 in volume 84, 1984.

For guidelines that are formed from one or more pieces (normally cubic Bezier curve pieces) a test is preferably used to determine if the described mapping approaches should be applied to each piece individually or if the described mapping approaches should think of the guideline as having a single path  $Q(t)$ . Specifically, if the end point of the  $n^{\text{th}}$  piece is the same as the starting point of the  $n+1^{\text{th}}$  piece and the normalized first derivative or normalized tangent vector evaluated at the end of the  $n^{\text{th}}$  piece is equal to that at the start of the  $n+1^{\text{th}}$  piece, then the  $n^{\text{th}}$  and the  $n+1^{\text{th}}$  pieces have sufficient continuity that is preferable to think of the pieces as a single continuous piece. If this test is not met, however, it is preferred to treat the pieces as discontinuous and separately map the bitmap brush to the  $n^{\text{th}}$  piece and the  $n+1^{\text{th}}$  piece. Alternatively, in the case of a

discontinuity, it would be possible to "miter" or otherwise join together the discontinuous ends of the pieces such that a single continuous path  $Q(t)$  is formed. An approach for creating virtual continuous paths from discontinuous pieces is described in C. S. Hsu, I. H. H. Lee, and N. E. Wiseman, "*Skeletal Stokes*," UIST '93 Proceedings of the ACM SIGGRAPH and SIGCHI Symposium on User Interface Software and Technology, November 1993. A further variation is to use discontinuous path segments to define a mapping, described subsequently, that generates warping brush effects with fewer calculations, and hence is significantly faster.

An alternative approach for painting with a bitmap brushes avoids visiting every pixel in the warped brush stroke more than once, and thus speeds up the underlying computations as much as ten-fold or more is illustrated in the flow chart in Figure 13. A guideline along which a brush stroke is to be warped is inputted. This guideline could be derived from a piece of clip art or be specified by a formula, could be discontinuous in its slope but is preferably, continuous over its entire length. However, discontinuous guidelines comprising a finite number of continuous segments can also be used, e.g., by considering each continuous segment separately. A convenient method is to use a fraction of the bitmap image corresponding to each continuous segment in a discontinuous guideline. Other choices, such as using non-contiguous fractions of the bitmap image are also possible in alternative embodiments.

The guideline is modified to generate a set of linear line segments, i.e., with a large radius of curvature (step 102). If the guideline contains sharp bends, i.e. regions with sharp curvature or corners then one or more line segments are inserted to smooth out the sharp corner. An advantageous strategy is to examine the angle between normals to

adjacent linear segments and flag a sharp corner in need of smoothing if the angle exceeds a threshold. Several strategies such as replacing the sharp corner with a miter join, a bevel or a round are used to handle such portions of the guideline.

At this point, the input guideline, which has at least one line, has been made  
5 piece-wise linear, as is shown in an exemplary manner in Figure 14, such that no two adjacent pieces are at a sharp angle. This restriction is employed to allow construction of suitable polygons (step 104), that are, preferably, convex polygons. For instance, polygons may be generated by constructing the sides of a polygon using lines drawn at a specified angle to each of the linear segments generated from the guideline. Figure 15  
10 illustrates such a construction relative to the line segments of Figure 14. In Figure 15, a polygon corresponding to line segment 0 is formed by the perimeter ABCD marked by corners A, B, C and D. Thus, in an embodiment the left endpoint of a linear segment may be used to draw a line segment normal to the linear segment having a total length equal to the desired brush thickness. This normal segment can serve as the right and the  
15 left boundaries of adjacent quads. In the case of a closed path the case is simple since there are no segments without flanking edges. If the guideline does not describe a closed path then an additional side is generated for a segment at one of the ends of the guideline to complete the definition of the quads along the guideline. It should be noted that there is no requirement that the sides of the polygons be generated by lines that are normal to a  
20 line segment of interest. Instead, a line at a specified angle to the line segment of interest is adequate to generate a desired side.

Conveniently, the sum of the length of the linear segments generated from the guideline may be used to proportionally divide the bitmap brush along its length into

rectangular segments, each of which is mapped to a corresponding polygon. Figure 16 illustrates an example of polygons generated in this manner. Preferably, this mapping results in assigning coordinates in the bitmap brush to the vertices of the polygons (step 106). Advantageously, when more than one line is included in the guideline to specify the thickness of the brush stroke, one of the lines is chosen consistently to estimate the length of the linear segments.

At this stage the last step 108 is carried out to render a warped brush stroke by mapping the pixels in a segment of the bitmap brush into a corresponding polygon. Advantageously, the number of linear segments determine the number of polygons created, and hence the number of corresponding segments of the bitmap brush that are mapped into the polygons.

Figure 17 illustrates the use of additional inputs to specify a varying thickness of a brush stroke. The use of polygons in the manner illustrated in Figures 13 and 16 makes this an attractive enhancement. The height of the brush stroke is constant in many of the embodiments described so far. This is not intended to be a limitation on the scope of the invention. For instance, use of a pressure sensitive device, e.g., a pressure sensitive graphics tablet, provides an input that may be used to vary the length of the lines defining the sides of a polygon. Similarly, the pressure input may also be utilized to modulate the opacity of the brush stroke during compositing the brush image with the underlying background image. In figure 17 line A'B' is at a variable distance from line AB where lines A'B' and AB together specify the path of a brush stroke and the separation between them specifies the thickness of the brush stroke. Figure 17 also shows some polygons

110 generated using piece-wise continuous segments of lines A'B' and AB as the top and bottom segments of the polygons 110.

Figures 18 and 19 illustrate some potential problems in rendering a warped brush stroke having sharp curves. Specifically, in portions of the guideline with a small radius of curvature, adjacent quads, or polygons, may lead to distorted polygons (Figure 18) or overlap (Figure 19). Overlaps, such as the ones illustrated in Figure 19 between polygons ABCD, CBEF and EFHG are likely to be significant when the radius of curvature is larger than the thickness of the brush stroke. Sharp curves shown in Figure 18 can be handled in the manner illustrated in Figure 20, i.e., by inserting additional linear segments such that adjacent line segments do not create sharp corners. The inserted segments are, then, used to generate polygons. In addition to this approach, one may represent a corner by a join treated as a miter, bevel or round. Thus, it may be possible to define a side of a polygon by a line segment in a line dividing, although not necessarily bisecting, the angle between lines drawn at the prescribed angle to the appropriate segment defining the sharp corner. A sharp corner may also be treated as a round, which then can be replaced with a set of linear segments to yield a construct similar to figure 20.

It has been observed that for well-behaved sharp curves, quads at the corner/sharp curve overlap such that their sides intersect at a point determined from the radius of curvature, as is shown in Figure 21. Thus, the overlap illustrated in Figure 19 can be addressed in accordance with Figure 21 to ensure that the warped brush stroke remains pleasing and continuous in its appearance. It is preferred that the corresponding segments of the bitmap brush image be proportionally truncated to enhance perceived the continuity of the warped brush stroke. Consequently, in such cases it may also be

possible to speed up the process of rendering the warped brush stroke by truncating the portion of the quads below (or above) the point of intersection since there are fewer pixels in the warped brush stroke to process.

In addition to these approaches, it is possible to define a side of a polygon by a line segment in a line drawn to divide, although not necessarily bisect, the angle between adjacent line segments obtained by making a piece-wise linear approximation to a guideline. This approach generates non-overlapping adjacent polygons even at sharp corners in light of the fact that the line segments intersect at the radius of curvature for the sharp corner and the line segment may be truncated as described above. Furthermore, these line segments result in evenly warped brush strokes at the corners. It is noteworthy that this method of generating sides of a polygon is not restricted to sharp bends or corners, and instead, may be used between any pair of linear segments that are close together following the generation of the piece-wise linear approximation to the guideline.

With the generation of the polygons, e.g., quads, for each of the linear segments generated from the guideline, a mapping is made to portions of the bitmap brush such that a fraction of the bitmap brush image maps to a particular polygon. One such mapping is shown in Figure 22 where the polygon 120 defined by perimeter ABCD maps to the middle segment 130 of the bitmap brush 180. Advantageously, adjacent bitmap brush fractions map to adjacent polygons.

Many mapping strategies are possible that range from visiting each pixel in the segment of the bitmap brush to those that use interpolation or other computational strategies to generate the pixels in the corresponding polygon. Notably, these strategies do not require visiting any pixel in the warped brush stroke more than once. Some

examples of such mapping are bilinear mapping and texture mapping. While many additional approaches and variations are possible, bilinear and texture mapping are described further by way of providing examples.

The bilinear transform maps a brush segment into a corresponding polygon  
 5 having four corners, i.e., a quad, such that the brush segment corners map into  
 corresponding polygon corners and the brush segment edges/sides map into polygon  
 edges/sides. However, diagonals in the brush segment need not be preserved as straight  
 lines in the corresponding polygon. Bilinear transforms are also termed as “corner-  
 pinning” transforms that preserve equispaced points along the edges but not diagonal  
 10 lines. Thus, for a point in the bitmap brush segment described by  $(x, y)$ , with  $x$  and  $y$   
 taking values in the interval  $[0, 1]$ , a pixel  $(u, v)$  in the corresponding quad defined by  
 corners  $(u_0, v_0)$ ,  $(u_1, v_1)$ ,  $(u_2, v_2)$  and  $(u_3, v_3)$  may be computed, for instance, as follows:

$$u(x, y) = u_0 + x(u_1 - u_0) + y(u_3 - u_0 + x(u_2 + u_0 - u_1 - u_3))$$

$$v(x, y) = v_0 + y(v_3 - v_0) + x(v_1 - v_0 + y(v_2 + v_0 - v_1 - v_3))$$

15 Unlike mapping from a rectangle to a quad, obtaining fractional values  $x$  and  $y$   
 when mapping from a quad to a rectangle includes the use of quadratics, and thus the  
 possibility of multiple solutions. This can be seen by noting the presence of coefficients  
 of  $xy$  in the equations above. Algorithms that address such complications are known and  
 exemplary discussions can be found in, e.g., Roger Crane, “*A Simplified Approach To*  
 20 *Image Processing*,” Prentice-Hall, 1997. In contrast to the bilinear transform, texture  
 mapping is even more flexible. Figure 23 provides a possible example of texture  
 mapping and bilinear mapping of a segment of a bitmap brush into a polygon. In Figure  
 23 the bitmap brush segment 150 is used to fill the polygon 140 as illustrated in Figure



22. Notably, in a bilinear transform, which is a special case of a texture map, corners 152, 154, 156 and 158 of bitmap brush segment 150 in Figure 23 would map to corners 142, 144, 146 and 148 respectively. Texture mapping uses a more general approach.

Texture mapping is a relatively efficient way to provide complexity in an image without the tedium of rendering every detail of a surface. In our case, a segment of a bitmap brush is mapped into a polygon using texture mapping. Texture mapping can be performed by mapping from the texture space to a two or three dimensional space using linear or non-linear functions. Another mapping from the two or three dimensional space to the target space, in this case the polygon corresponding to the bitmap brush segment, completes the texture map. Further details of and variations on texture mapping are found in Paul S. Heckbert, "*Survey of Texture Mapping*," IEEE Computer Graphics and Applications, November 1986, pages 56-67.

As will be appreciated, the subject invention has the advantage of producing highly realistic artistic or photo stroke images. Among other things, this realism is accomplished by the aforementioned methods which particularly provide for the axial compression of the bitmap brush on the concave side and the axial stretching of the bitmap brush on the convex side when rendering the paint stroke. This is illustrated in Figures 24 and 25 for a "line" drawing and a "checkered" bitmap brush respectively.

Figure 26 provides an illustration of a method and a system in accordance with an embodiment of the invention. A linearization module is used to generate a piece-wise linear approximation to a curved guideline in step 200. This first approximation is improved, for instance, in step 210 by using a sharp-corner-detecting module to flag sharp corners and, subsequently, adding linear segments to remove the sharp corners. Of

course, in some embodiments, such corners may not be removed for artistic or other reasons. Thus, such removal is not necessary, but merely a desirable operation. Polygons corresponding to the linear segments are generated in step 220 using a polygon-generating module. A default mapping or a mapping specified by a user, is used in a mapping module to identify and/or define segments in the bitmap brush corresponding to each of the polygons. Finally, a rendering module carries out the calculations and operations to actually output the warped brush stroke.

All of the references cited herein, including patents, patent applications, and publications, are hereby incorporated in their entireties by reference. In particular, patent application 09/224,237, assigned to the assignee of this application, is incorporated by reference in its entirety.

In view of the many possible embodiments to which the principles of this invention may be applied, it should be recognized that the embodiment described herein with respect to the drawing figures is meant to be illustrative only and should not be taken as limiting the scope of invention. For example, those of skill in the art will recognize that the elements of the illustrated embodiment shown in software may be implemented in hardware and vice versa or that the illustrated embodiment can be modified in arrangement and detail without departing from the spirit of the invention. Therefore, the invention as described herein contemplates all such embodiments as may come within the scope of the following claims and equivalents thereof.